

MICRO-DEVICE ASSEMBLY WITH ELECTRICAL CAPABILITIES

Background of the Invention

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The present invention is directed to assemblies configured using micro-electromechanical systems (MEMS) and micro-systems technology, and more particularly to improved micro-assemblies which have electrical capabilities.

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~~The use of micro-hinges has become prevalent with the increased utilization and complexity of surface micro-machined components and systems. Typically used in the implementation of out-of-plane or vertically oriented micro-device designs, the micro-hinge is usually fabricated in a minimum two-layer, though typically three-layer, polysilicon process. Such a hinge, known as a staple hinge, is illustrated in FIGURE 1 integrally connected with micro-mirror 12, and is used to attain out-of-plane motion. The multi-step fabrication process, includes depositing a layer which is then patterned and etched. Next a second layer is deposited, patterned and etched in such a way that after removing any filling material, the first layer is free to move in a prescribed path, while being held in place by the second layer. This structure creates a rotating joint implemented in MEMS or micro-systems to permit for the mechanical movement required for out-of-plane or vertically oriented devices.~~

While the described staple hinge provides a useful mechanical function, a drawback is the difficulty to incorporate electrical connections between the hinges and

1 the micro-element to which it is attached. This
2 difficulty is illustrated in FIGURE 1, where it is shown
3 that the lifted structure, i.e. micro-mirror 12 is
4 floating above substrate 14. Providing an electrical
5 connection between these physically separated elements
6 raises significant obstacles to implementing a three-
dimensional electrically actuated MEMs device such as an
electrostatically driven micro-mirror. In order to
realize scanning of a mirror, it is necessary for the
7 mirror to be pushed and/or pulled mechanically by an
actuator placed on substrate 14. Therefore it has been
deemed desirable to develop micro-assemblies which are
capable of providing an electrical connection between a
hinge element and a micro-device, using a simplified
structural arrangement.

Summary of the Invention

~~Provided is a micro-electromechanical assembly~~
including a micro-device formed in the device layer of a
silicon-on-insulator substrate. A ribbon structure is
8 formed in the same device layer, where the ribbon
structure is less than the thickness of the micro-device.
A connection interface provides a connection point between
a first end of the micro-device and a first end of a ribbon
structure, wherein the ribbon structure and micro-device
25 are integrated as a single assembly. An electrical
conductor is formed extending from one end of the ribbon
structure to the micro-device tethered at the other end.

Brief Description of the Drawings

FIGURE 1 is directed to a micro-mirrored assembly using multiple polysilicon layers for implementation of a micro-hinge;

FIGURE 2 is an isometric view of a ribbon micro-hinge attached to a micro-device according to the teachings of the present invention;

FIGURE 3 is a side view of the ribbon hinge and micro-device of FIGURE 2;

FIGURE 4 sets forth the processing steps for formation of the ribbon structure attached to a micro-device in accordance with the teachings of the present invention;

FIGURE 5 depicts a top view of the processing of an isolation groove in a micro-device;

FIGURE 6 illustrates a further embodiment of the formation of isolation grooves in the micro-device and the ribbon structure;

FIGURE 7 sets forth a conductor material deposited on the ribbon structure and the isolation grooves; and

FIGURE 8 sets forth a completed structure implementing the concepts of the present invention.

Detailed Description of Preferred Embodiments

~~While Figure 1 depicts a micro-assembly implementing a polysilicon staple/door-hinge, FIGURES 2 and 3 illustrate a micro-assembly 18 having a ribbon hinge 20 integrated with micro-device 22, such as a micro-mirror. The micro-mirror device 22 has been moved from an in-plane position to an angle of approximately 30°. Movement of the mirror is achievable by a variety of mechanisms, including the use of a micro-probe or an actuator.~~

Ribbon hinge 20 is, therefore, designed to replace the widely used polysilicon staple-hinge design illustrated in FIGURE 1. Ribbon hinge 20 is a single-crystal-silicon (SCS) component which has mechanical stability, and which is configured using a simplified processing procedure. Thus, ribbon hinge 20 of the present invention provides a flexible mechanism as opposed to the jointed staple-hinge of FIGURE 1.

Ribbon hinge 20 is formed from the device layer of a silicon-on-insulator wafer, which has been thinned down to allow increased mechanical flexibility. This design produces a high quality mechanical structure having sufficient strength for its intended purpose.

FIGURES 2 and 3 emphasize the flexibility of ribbon hinge 20. In this embodiment, ribbon hinge 20 is approximately 500nm thick, approximately 50 μ m wide and approximately 140 μ m in length. Micro-assembly 18, including ribbon hinge 20 and mirror 22 is fabricated using a silicon-on-insulator (SOI) wafer with a device layer thickness of approximately 3 μ m and a buried oxide (BOX) layer thickness of approximately 2 μ m.

In a two-mask process used to manufacture the micro-assembly 18, the bulk area around mirror 22 and other protected areas is etched in a time-etch process leaving approximately 500nm of the device layer silicon. The ribbon hinge is then patterned and the exposed surrounding 500nm thick silicon (Si) device layer material is removed in a dry-etch process. This leaves the mirror structure, protected by an oxide layer, and the thin silicon ribbon hinge 20 resting on the sacrificial BOX layer. Following processing (e.g. BOX

and Hydrofluoric Acid (HF) 49% processing), and subsequent drying procedures, mirror 22 is freed to move.

As will be discussed in greater detail below, the formation of a micro-assembly having a ribbon hinge and an integrated micro-device is a two-step process in the sense that in the first step a micro-device, such as mirror 22 is patterned and etched. Then a second procedure is used for thinning down and forming ribbon hinge 20. It is of course possible to inverse these processes by thinning the ribbon layer first and then processing the out-of-plane device area. An issue in this regard is that the micro-device and ribbon hinge are all formed from the same material layer. The difference between the ribbon hinge and micro-device is the geometry of the patterning, and the physical thickness of the areas. Etching ribbon hinge 20 to a much thinner cross-section than micro-device 22, permits increased flexibility of the ribbon hinge 20. The flexibility of ribbon hinge 20 is illustrated by its almost S-shape.

The methodology that incorporates fabrication of the ribbon hinge structure in the same material as the out-of-plane device such as the mirror, has many advantages over existing hinge technologies, including a simplified fabrication process. For example, since the hinge is fabricated using the same material layer as that of the micro-device, there is no adhesive joint or holding structure necessary between the hinge and the attached micro-device. Such a design accommodates the high mechanical torque and forces delivered by the attached micro-device without comprising the integrity of connection point 24.

A further advantage of the ribbon hinge configuration discussed above, is to use the ribbon hinges for an electrical connection between the ribbon hinge to the micro-device. Particularly, having ribbon hinge and micro-device formed from the same device layer of the silicon-on-insulator wafer allows for the implementation of a three-dimensional electrically actuated MEMs or micro-assembly. The fabrication process which permits the placement of an electrical connector from a ribbon hinge to a micro-device, is set out in more detail particularly in connection with FIGURES 4-8.

Turning to FIGURE 4, illustrated is a process flow for fabrication of a single crystal silicon ribbon hinge integrated with a micro-device, and having an electrical conductor running from ribbon hinge and to the micro-device, according to the present invention. In step 28, the process begins with a clean silicon-on-insulator (SOI) wafer 30 having a single crystal silicon device layer 32, a buried oxide layer 34, and a substrate layer 36. In a first step of the process, 38, a photo-resist layer 40 is deposited on device layer 32 using standard lithographic processes. Photo-resist layer 40 is patterned in such a way as to expose the area to be thinned into the ribbon hinge 42. In a next step 44, a wet etching process is undertaken such as wet etching with a potassium-hydroxide (KOH) 45% solution at 60°C. The wet etching causes the exposed ribbon hinge area 42 of device layer 32 to be removed to a thickness of approximately 500nm.

In step 46, previously applied resist layer 40 is removed prior to a repatterning for etching of the out-

of-plane device, an island area, an anchor structure and an isolation groove.

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~~Following removal of first photo-resist layer 40,~~
second resist layer 48 is applied on the top surface of SOI 30. In step 50, a dry etching process is undertaken on the exposed silicon of device layer 32 to form the out-of-plane device 52, as well as the island area 54, anchor structure 56 and isolation region or groove 57.

Turning to FIGURE 5, set forth is a top view of step 58 of FIGURE 4. Ribbon hinge 42 is shown connected to anchor portion 56 at a first end and to micro-device 52 at a second end. Patterned within micro-device 52 is an isolation region 57. As will be discussed in greater detail below, isolation region 57 is patterned within micro-device 52 to isolate an electrical conductor to be deposited therein from the remainder of micro-device 52. It is to be appreciated that an isolation groove may also be patterned within the ribbon structure 42 and anchor 56. The additional areas where isolation grooves may be etched are shown in FIGURE 6, which may be considered a further embodiment of the etching process shown in FIGURE 4. Herein, two isolation regions 57A and 57B are etched into micro-device 52. Isolation regions 57C and 57D are also to be etched within ribbon structure 42 through anchor 56. FIGURE 6 emphasizes that multiple conductor lines may be processed on a single ribbon hinge 42 and/or micro-device 52. It is also to be understood that multiple ribbon hinges may be attached to a single micro-device.

Returning to FIGURE 4, in step 58, the second layer of photo-resist 48 has been removed, and an etching

process is started to begin etching the exposed buried oxide layer 60, using a Hydrofluoric Acid (HF) 49% solution.

Next, in step 62, the third and final layer of photo-resist 64 is deposited and patterned on the SOI wafer 30. This final photo-resist layer 64 is to be used during the buried oxide-release (BOX) operation, wherein ribbon hinge 42 and micro-device 52 are released by etching all unprotected buried oxide. Prior to releasing the micro-assembly, as shown more particularly in FIGURE 7, a depositing step, deposits an electrical conductive material 65 within isolation region 57 and on ribbon structure 42. It is to be understood that same conductive material may be deposited within the isolation regions 57A-57D of FIGURE 6.

~~Once electrical conductive material 65 has been deposited, the buried oxide release (BOX) operation is undertaken, whereafter, as shown in step 66 of FIGURE 4, the only remaining buried oxide layer material 68 and 70 is under the island structure 54 and the anchor section 56. The remaining buried oxide material is removed such that a separation layer 72 and separation edge 74 are void of such material. Removal of the buried oxide allows for the movement of the micro-device 52 and ribbon hinge 42. In step 68, it is noted that all remaining photo-resist is removed, for example by a dry O₂ plasma-etch process.~~

Thus, step 68 depicts the original SOI wafer 30 as a micro-device and hinge assembly, with a conductor.

Turning to FIGURE 8, set forth is a completed micro-assembly 80 according to the teachings of the present

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invention. More particularly, a ribbon hinge 42 as described in the foregoing, is integrally attached at a first end to a micro-device 52 and at a second end to an anchor portion 56. Micro-device 52 includes an etched isolation region 57. Deposited within isolation region 57 is a conductive material 65 which is also deposited on ribbon hinge 42 and within an isolation groove of anchor 56. An electronic device 76 is in operational connection to the electrical conductor material 65 within isolation region 57. A power source 78 is in connection with the electrical conductor material 65, at an opposite end by anchor portion 56. Electronic device 76 may be activated upon application of electrical power from electrical power source 78. Further, electrical device 76 may be any one of a number of devices such as an actuator to ~~assist in movement of micro-device 52.~~

While the present invention is described with respect to a preferred embodiment, it would be apparent to one skilled in the art to practice the present invention into other configurations and designs. Such alternate embodiments would not cause departure from the spirit and scope of the present invention.